



UNIVERSITY OF RUHUNA

Faculty of Engineering

End-Semester 2 Examination in Engineering: March 2014

Module Number: IS2401

Module Name: Linear Algebra & Differential Equations

[Three hours]

[Answer all questions, each question carries 14 marks]

Write your answers for PART A and PART B in separate booklets

PART A

Q1. a) Solve the initial value problems

i. $x \frac{dy}{dx} = y + \sqrt{x^2 - y^2}; \quad y(x_0) = 0, \text{ where } x_0 > 0.$

ii. $y'' - 3y' + 2y = 3e^{-x} - 10 \cos 3x.$

[5.0 Marks]

b) Suppose that an airplane departs from the point $(a,0)$ located due east of its intended destination to an airport located at the origin $(0,0)$. The plane travels with constant speed v_0 relative to the wind, which is blowing due north with constant speed w_0 . As indicated in Figure Q1a, we assume that the plane's pilot maintains its heading directly toward the origin. Figure Q1b derives the plane's velocity components relative to the ground as follows.

$$\frac{dx}{dt} = -v_0 \cos \theta = -\frac{v_0 x}{\sqrt{x^2 + y^2}}$$
$$\frac{dy}{dt} = -v_0 \sin \theta = -\frac{v_0 y}{\sqrt{x^2 + y^2}} + w$$

Hence, the trajectory $y = f(x)$ of the plane satisfies the differential equation

$$\frac{dy}{dx} = \frac{dy/dt}{dx/dt} = \frac{1}{v_0 x} (v_0 y - w \sqrt{x^2 + y^2})$$

By setting $k = w/v_0$, find the equation of the plane's trajectory for the initial condition $v(a) = 0$.

[5.0 Marks]

c) Suppose $a = 200 \text{ min}$, $v_0 = 500 \text{ min/h}$, $w = 100 \text{ min/h}$, and then $k = w/v_0 = 1/5$; so the plane will succeed in reaching the airport at $(0,0)$ with these values equation of the plane trajectory yields

$$y(x) = 100 \left[\left(\frac{x}{200} \right)^{4/5} - \left(\frac{x}{200} \right)^{6/5} \right]$$

If we want to find the maximum amount by which the plane is blown off course during its trip, what is the maximum value of $y(x)$ for $0 \leq x \leq 200$?

[4.0 Marks]

Q2.

- a) What is meant by
- an ordinary point
 - a regular singular point of a differential equation

$$P(x) \frac{d^2y}{dx^2} + Q(x) \frac{dy}{dx} + R(x)y = F(x)$$

[2.0 Marks]

- b) Show that the infinity is a regular singular points of the differential equation

$$2x^2 \frac{d^2y}{dx^2} + x \frac{dy}{dx} - \left(\frac{1}{x^2} + 1 \right) y = 0$$

Solve the above equation about infinity.

[6.0 Marks]

- c) Sketch the region R in the xy plane bounded by
- $y = x^2, x = 2, y = 1$.
 - Give a physical interpretation to $\iint_R (x^2 + y^2) dx dy$
 - Evaluate the double integral in ii).

[6.0 Marks]

Q3.

- a) Calculate the normal of inertia of the spherical shell $x^2 + y^2 + z^2 = 1$ ($z \geq 0$) with the density μ_0 about the z -axis.

[4.0 Marks]

- b) State
- The divergence theorem
 - Stockes' theorem.

[2.0 Marks]

Verify the divergence theorem for $A = (2x - z)\mathbf{i} + x^2y\mathbf{j} - xy^2\mathbf{k}$ taken over the region bounded by $x = 0, x = 1, y = 0, y = 1, z = 0, z = 1$.

[4.0 Marks]

- c) If V is the volume bounded by the closed surface S and \mathbf{n} is the outward unit normal to surface S at the point (x, y, z) , prove that
- $\iiint_V (\nabla \times A) dV = \iint_S (\mathbf{n} \times A) dS$
 - $\int_C \phi dr = \iint_S (\mathbf{n} \times \nabla \phi) dS = \iint_S ds \times \nabla \phi$

[4.0 Marks]

PART - B

- Q4. a) Briefly define the following terms.
- i. Subspace of a vector space.
 - ii. Linear independence of set of vectors.
 - iii. Basis for a vector space.
 - iv. Dimension of a vector space. [2.0 Marks]
- b) Which of the following subsets is a subspace of \mathbb{R}^3 ? Justify your answer.
- i. $W = \{(1, x_1, x_2) \mid x_1, x_2 \in \mathbb{R}\}$
 - ii. $W = \{(x_1, x_1 - x_2, x_2) \mid x_1, x_2 \in \mathbb{R}\}$ [2.0 Marks]
- c) Determine whether the following set of vectors S is linearly independent or linearly dependent. Justify your answer.
- i. $S = \{v_1, v_2, v_3\} = \{(1, 2, 0, 1), (2, -1, 1, 0), (0, 5, -1, 2)\}$
 - ii. Let $A = \begin{bmatrix} -1 & 1 \\ -1 & 0 \end{bmatrix}$ and $S = \{A, A^2, A^3\}$ [3.0 Marks]
- d) Show that $W = \{(x_1, x_2, x_3) \in \mathbb{R}^3 \mid x_1 + x_2 + x_3 = 0\}$ is a subspace of \mathbb{R}^3 . Then find a basis for the subspace W . Determine the dimension of W . [3.0 Marks]
- e) Which of the following functions are linear transformations? Justify your answers.
- i. $T : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ defined by $T(x, y, z) = (x + y + z + 1, 0)$
 - ii. $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ defined by $T(x, y) = (\sin x, \cos y)$ [4.0 Marks]

- Q5. a) If $\lambda_1, \lambda_2, \dots, \lambda_n$ are eigenvalues of a matrix A , prove the followings:
- i. The inverse matrix A^{-1} has eigenvalues $\frac{1}{\lambda_1}, \frac{1}{\lambda_2}, \dots, \frac{1}{\lambda_n}$.
 - ii. The matrix $(A - kI)$ has eigenvalues $(\lambda_1 - k), (\lambda_2 - k), \dots, (\lambda_n - k)$.
 - iii. The matrix A^2 has eigenvalues $\lambda_1^2, \lambda_2^2, \dots, \lambda_n^2$.
 - iv. If A is upper triangular, then the eigenvalues are exactly the main diagonal entries. [4.0 Marks]

- b) Find the eigenvalues and eigenvectors of A and $(A - 4I)$. Find the trace (A^3).

$$A = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 2 & 0 \\ 2 & -2 & 3 \end{bmatrix} \quad \text{[6.0 Marks]}$$

- c) Diagonalize the matrix A in part b. [4.0 Marks]

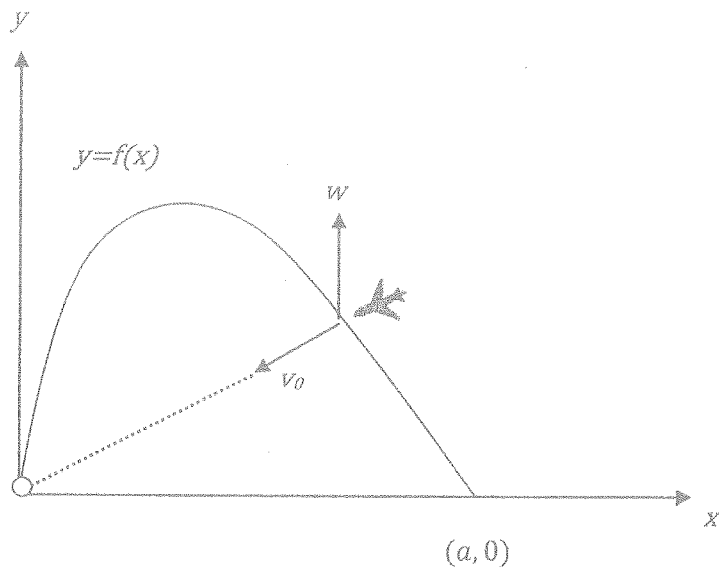


Figure Q1a: The airplane headed for the origin

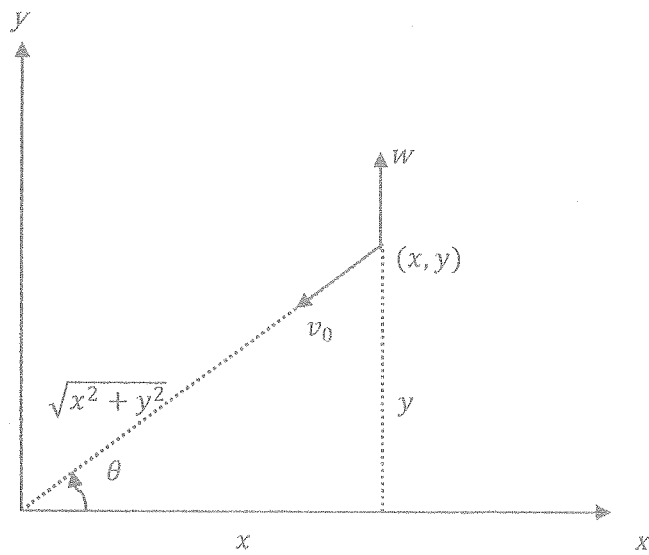


Figure Q1b : The components of the velocity vector of the airplane